Evaluating the Effectiveness of Military Decision Support Systems: Theoretical Foundations, Expert System Design, and Experimental Plan

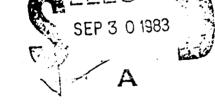
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Integrated Sciences Corporation

BASIC RESEARCH



U. S. Army



Research Institute for the Behavioral and Social Sciences

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The technical approach consists of simulating expert systems in a game-like environment. Such (1) friendly and English-like (stylized) dialogue of rationale about decision recommendations, (3)	characteristics include ,(2) system explanations

Item 20 (continued)

relevant suggestions and comments about situation assessments and about plans proposed by the user, and (4) the use of high level strategic concepts and terminology.

The required software for such a program includes (1) a game environment simulator, (2) a simulated expert system for the game, and (3) an evaluation program for recording execution histories and for summarization. The game simulator will contain provisions for the experimenter to adjust critical parameters so that a controlled environment can be maintained. The expert system will monitor the progress of the game and can be interrogated as the user sees fit. A facility will also be provided for evaluating the user's performance under different modes of consultation with the expert system.

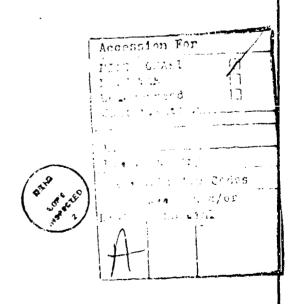


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I. INTRODUCTION

1.1 Program Objective

The main objective of this program is to construct a flexible testbed for the evaluation of the effectiveness of computer-based expert systems in military training and planning.

1.2 Approach

The technical approach consists of simulating the characteristics of expert systems in a game-like environment. Such characteristics include (1) friendly system user interaction, (2) system explanations of rationale about decision recommendations, (3) an ability to make relevant suggestions and comments about situation assessments and about plans proposed by the user, and (4) the use of high-level strategic concepts and terminology.

The required software for such a program includes (1) a game environment simulator called the "Scenario Generator".

(2) a simulated expert system for the game called the "Expert Aid", (3) an Optimality Algorithm for computing the best decisions in any situation, and (4) an Evaluation Module for recording execution histories and performance parameters. The expert system will monitor the progress of the game and can be interrogated as the user sees fit. A facility will also be provided for evaluating the user's performance under different modes of consultation with the expert system.

1.3 Progress

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To date, the following progress has been made on the design and implementation of the expert system.

- (1) Design of the Scenario Generator.
- (2) Prototype implementation of the Scenario Generator game for testing purposes.
- (3) Completion of the Optimality Algorithm Design.
- (4) Implementation and execution of Optimality Algorithm resulting in a set of optimal decision tables.
- (5) Design of the Expert System and integration into the existing Scenario Generator.
- (6) Design of the Experimental Plan.

Plans for project continuation include the following major tasks.

- (1) Implementation of the full expert system including system explanations of recommendations.
- (2) Implementation and integration of the Evaluation Module for measuring user performance.
- (3) Completion of the evaluation experiments.

II. THEORETICAL FOUNDATIONS

2.1 Expert Systems with Ground Truth

In a problem environment involving multiple decision points, "ground truth" is a complete description of the optimal strategy for all possible situations the decision maker may encounter. These optimal decisions must be identifiable by computation and must not be dependent upon the judgment of humans regardless of their expertise. An expert system, armed with ground truth, could make perfect recommendations to the decision maker at all times. If the environment contains uncertain events, the ground truth can be accurate only up to the highest expected utility. That is, ground truth may not guarantee successful outcomes; it just means that no other decision strategy could produce better performance in the long run.

Ground truth, then, is a property of the environment and not of the expert system. Most expert systems do not have built-in ground truth. Their recommendations are based on human knowledge and experience encoded as rules. The reason for this is obvious. Any environment complex enough to warrent the construction of an expert system is usually too complex to compute ground truth. However, the existence of ground truth permits the calibration of performance measures in expert system evaluation. Learning curves for new users could be generated by comparing decision performance with and without the recommendations of the expert system, but the results would be unreliable since the user's expertise continuously increases simply from contact with the environment. On the other hand, ground truth provides an upper bound on performance and a standard against which performance can

be measured. In an environment containing uncertain events, evaluation without ground truth must rely on the outcomes of the decisions rather than on the quality of the decisions themselves. The results would then be clouded by the random processes within the environment. With ground truth as a standard, precise measurements of decision performance can be attained regardless of the outcomes of the experiments.

2.2 Scenario Generator Requirements

The task, then, is to devise a decision environment which is complex enough to be challenging to a decision maker and, yet, simple enough to permit the calculation of ground truth. These objectives lead to the following requirements for the expert system testbed Scenario Generator.

- (1) Environment complex enough to be challenging to a decision maker.
- (2) Environment simple enough to calculate ground truth.
- (3) Environment amenable to the construction of and use of an expert system for decision recommendations.
- (4) Environment containing uncertain events.
- (5) Environment containing information feedback during the decision process.
- (6) Environment within the military domain and which embodies a military decision problem.

Since uncertain events and information feedback are common elements of decision environments, their inclusion in the Scanario Generator is important for the transfer of evaluation results to real-world expert systems.

The selected environment that satisfies the above criteria is a military decision game. An expert system designed around a game would provide recommendations about the best "moves" in different situations. Ground truth can be established (if the game is not too complex) since the criteria for winning and losing are specified precisely in the rules. The only disadvantage is that games are not generally very realistic. However, as will be shown in the next section, a methodology can be described which will permit the construction of a ground truth expert system in any environment. The experimental results will then be transferrable.

2.3 The General Model

The scenario game environment is founded upon a general model for a class of ground truth expert systems. The major components of the model that characterize the environment are:

- (1) Well-defined decision points with all choice options specified in advance.
- (2) Well-defined event points with all outcomes and associated probabilities specified.

(3) Well-defined information feedback points with all possible combinations of "reports" specified.

Figure 1 shows notational symbols for each of the components: decision points, event points, and report points. An "identification point" is a place during the decision process where an important observation is made when it does not coincide with one of the other components. By connecting symbols together to form a tree, a class of decision environments can be constructed which leads directly to the design of the ground truth expert system.

A complete decision structure should have the following characteristics.

- (1) Start with a decision point.
- (2) Possess normalized probabilities on each branch leading out from an event point.
- (3)Possess utility values on every termination branch.

Once built, the decision structure dictates the procedure for calculating the ground truth. At every decision point, the value of the decision (for all possible situations) is equal to the maximum of the values on its branches. At every event point, the value of the event is equal to the expected value of the utilities and probabilities on its branches. At every report point, the utility of the information is equal to the utility of its branch given the probability of the report. Thus, decision utilities are calculated by a "rollback" procedure that begins at the terminal branches and ends at the initial decision point. These calculations must be performed for every combination of decision situation and every combination of report outcome. In other words, a single

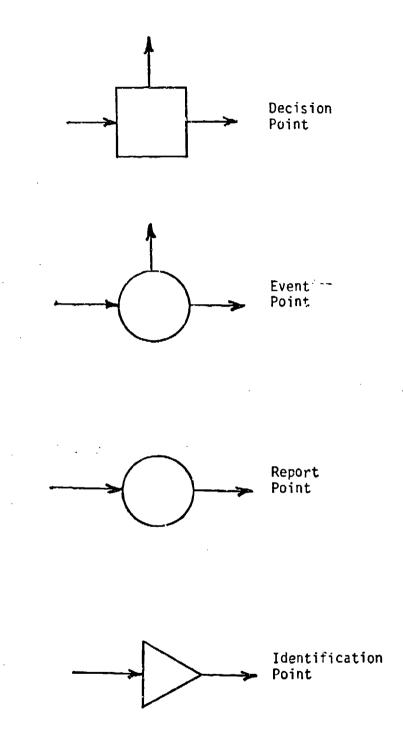


Figure 1. Decision Diagram Elements

tree diagram shows the sequential decisions that must be made, but the decision maker could be faced with the sequence over and over again in a repetitive environment in which situational parameters (such as resources, etc.) are different each time. This leads to a complex series of matrices necessary to rollback the utility values and calculate the optimal decisions at every decision point. The "Military Breakthrough" game, designed as an experimental testbed, satisfies the requirements of the general model and illustrates how these utility calculations are made and how they lead to the construction of the corresponding expert system.

III. THE EXPERT SYSTEM

.3.1 Optimal Decision Tables

The 140 decision tables provide the optimal decisions for any situation encountered in the simulation game. Appendix B contains a complete listing of all tables arranged on 28 pages: one page for each combination of enemy line (1-4) and enemy encampment (1-7). Five tables are associated with each situation.

Table 1: Attack/Continue/Shallow/Deep

Table 2: Attack/Continue given Shallow, not detected

Table 3: Attack/Continue given Shallow, detected

Table 4: Attack/Continue given Deep, not detected

Table 5: Attack/Continue given Deep, detected

Table 1 is used when the player encounters a new enemy encampment and is faced with the decision of whether or not to send out reconnaissance (See Figure 2). If reconnaissance is chosen, a secondary decision is required to determine the type: shallow (S) or deep (D). However, if the player decides not to send reconnaissance, he is left with the decision to immediately attack (A) or continue (C) to the next enemy position. The optimal decisions for these 4 choices appear in Table 1.

The actual optimal decision depends upon 3 factors: (1) the current position, (2) the current strength of the friendly forces, and (3) the first report (X1) received by the player on the status of the strength of the enemy forces. Thus, decision Table 1 on each of the 28 pages in the listing in the Appendix is 12x64 in size, one row for each of the 12 possible friendly force combinations and one column for each of the 64 possible X1 reports. The last line, showing a friendly force of zero, is omitted since the game would be over and no further decisions could be made.

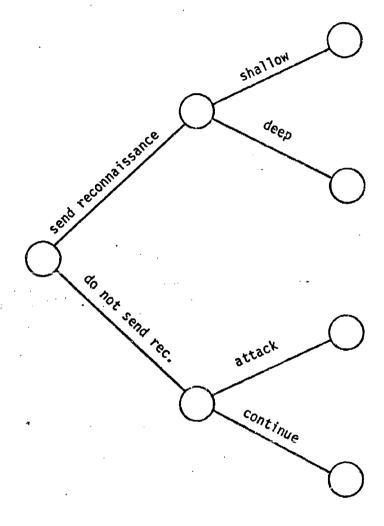


Figure 2. Table 1 Decisions

For example, if the player is facing enemy line #1 and enemy encampment #3 with a force of MHH (meduim strength artillery, high strength infantry, and high strength tanks) and observes that the report for the enemy strength is NNL (nil, nil, low reading from top-to-bottom), the optimal decision would be "D", ("take Deep reconnaissance").

Tables 2 and 3 are used only when the player has chosen shallow (S) reconnaissance for the initial decision (Table 1). Table 2 is used if the reconnaissance force is not detected and Table 3 is used if the force is detected. For these two tables, only the decisions of attacking (A) or continuing (C) are relevant. The column labels at the top of the page still apply, but now represent the outcome of report X2, a more accurate portrayal of the true enemy strength. Some of the entries in Tables 2 and 3 are missing since these particular combinations are impossible for report X2.

Tables 4 and 5 at the bottom of each page are used if deep (D) reconnaissance is made for the initial decision in Table 1. Again, two tables are required, Table 4 for "not detected" and Table 5 for "detected". In these cases, however, only 4 columns are necessary since the true enemy strength is known to the player at this time (as the result of report X3) and can be only 1 of 4 possible combinations.

Thus, as can be seen in Figure 3, S and D are intermediate decision points whereas A and C are final decision points. Numbers inside circles refer to the Tables used.

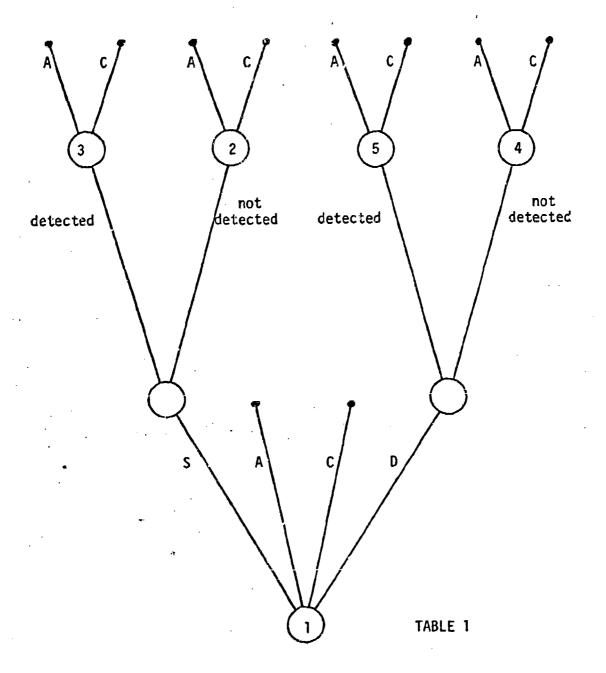


Figure 3. Player Decisions

3.2 Expert Rule Formation

An expert system, which had access to all 140 decision tables, could give optimal recommendations for every encountered situation. However, such information may not be the most valuable to a user. One of the purposes of an expert system is to teach the human user enough about the characteristics of the application environment so that he acquires some expertise. As they now exist, the decision tables are far too complex to learn, especially by point recommendations as individual situations are encountered during simulation exercises.

A more useful set of recommendations would be based on general rules that capture most, but not necessarily all of the optimal decisions. By observing the optimal tables listed in Appendix B, it is clear that most of the decisions fall into clusters. Thus, an expert system "rule" can be defined as a single recommended decision which represents the majority of optimal decisions within a specified region of the decision space.

The accuracy of the expert system will ultimately depend upon the uniformity of decisions within selected clusters. The accuracy can, thus, he calculated precisely. It is simply the total percentage of correctly classified decision points. The clusters should be chosen in such a way to produce high accuracy while reducing the cognitive complexity associated with learning the rules.

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Figure 4. Decision Table Clusters

3.3 Expert Rules for the Simulation Game

The decisions for a single table are composed of a naber of connected rules, one rule for each rectangular region. Figure 5 shows the divisions for encampment #3 in enemy line #3.

Table 1 has 3 distinct rectangular clusters and i non-rectangular region covering the remainder of the table. To specify the rules, only the bounderies for the columns and rows are necessary. Thus, the upper left-hand cluster (with mostly A's) falls between 0 and 2 in enemy strength and between 7 and 9 in friendly strength. A set of 3 rules would be required to completely describe Table 1. The following form shows this specification using "E" for the enemy strength and "F" for the friendly strength.

RULE #	<u> </u>	<u>E ≤</u>	≼ F	<u> </u>	<u>DO</u>	ELSE
1	0	2	7	9	A	2
Ž	O	3	. 5	5	. А	3
.3	0	9	0	4	S	D

The above description can be read as follows:

- (1) If the enemy strength is between 0 and 2 and the friendly strength is between 7 and 9, attack (A), otherwise follow Rule 2.
- (2) If the enemy strength is between 0 and 3 and the friendly strength is equal to 5, attack, otherwise follow Rule 3.
- (3) If the enemy strength is between 0 and 9 and the friendly strength is between 0 and 4, send shallow reconnaissance (S), otherwise send deep reconnaissance (D).

The last decision recommendation in the last rule (D) covers the non-rectangular portion of the table.

DECISION	MAP	ENEMY LINE 3 ENCAMPMENT 3 (1=2, J=5)
ATTACK/CONTIN	۱ د	NNNLALLANWELTHINHHEINHEINNALLHINNMIHHLLHEMNHHLLMMHHILMMHHILHHMHHHHHINLAN LANNALLHINNMIHHHINNMIHHLHINNMIHHHINNMIHHHINNMIHHHINNMIHHHINNMIHHHINNMIHHHINNMIHHHINNMIHHHINNMIHHHINNMIHHHINNMIHHHINNLAN LANDA DEBAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAA
ى مەرە		ADADDODDDDDDDDDDDDDDDDDDDDDDDDDDDDDDDD
ATTACK/CG	PITIES HITTIES S	VEN SHALLOW, NOT DETECTED (REPORT X2) AAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAA
	7 2 2 2 .J	AAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAA
700 Y 100 Y	ZITZIZZZZZZZZZZZZZZZZZZZZZZZZZZZZZZZZZ	KAAAAAAAAAAAA
ATTACK/CC	-	CCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCC
	Z. Z	(REPORT X3) (REPORT X3) (CA A A A A A A A A A A A A A A A A A A

Figure 5. Example Clustering

Obviously, the accuracy of the resulting rules depends on the accuracy of the individual regions. For the example table described above, the accuracy of the rules is shown in the following chart.

Region	Correct	<u>Total</u>	% Correct	Decision
1	41	50	82%	Α
2	36	40	90%	Α
3	79	128	62%	S
4	484	506	96%	D
Total	640	704	91%	•

Thus, the expert rules for this particular decision table are 91% correct.

The figures on the following pages list all 115 rules contained in the current preliminary version of the Expert System. Figure 6 cataloges the 5 main tables for each of the 28 positions and their associated first rule numbers. For example, if the player is facing enemy line #3 and encampment #1 and is considering a decision about reconnaissance (Table 1), the applicable rule is #68.

Figure 7 contains the actual rules. If both enemy strength conditions (E) and both friendly strength conditions (F) are true, the decision under the "DO" column should be followed where "A" means attack, "S" means take shallow reconnaissance, "D" means take deep reconnaissance, and "C" means continue (no attack). If any of the 4 conditions fail, the instructions under the "ELSE" column should be followed. These instructions are either (1) a decision: A, S, D, or C, or (2) a reference number which indicates the next rule to follow.

Enemy Line	Enemy Encampment	<u>Table</u>	Rule #		Enemy Line	Enemy Encampment	<u>Table</u>	Rule #
1	1	1	1	•	· 2	1	ì	35
1	1	2	2		2	1	2	40
1	1	3	2		2	ı	3	41
1	1	4	3		2	1	4	42
1	1	5	3		2	1	5	3
1	2	1	7		2	2	1	43
1	2	2	4		2	2	2	40
1	2	3	2		2	2	3	45
1	2	4	3		2	2	4	42
1	2	5	3		2	2	5	3
1	3	1	5		2	3	1	46
1	3	2	4		2	3	2	47
1	3	3	6		2	3	3	45
1	3	4	3		2	. 3	4	42
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1	4	1	7		2	4	1	48
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1	4	5	12		2	4	5	12
ı	5	1	13		2	5	1	56
1	5	2	19		2	5	2	60
1	5	3	21		2	5	3	62
1	5	4	23		2	5	4	23
1	5	5	12		2	5	5	12
1	б	ì	24		2	6	1	64
1	6	2	31		2	6	2	67
1	6	3	33		2	6	3	61
1	6	4	34		2	6	4	34
1	6	5	23		2	6	5	23

Figure 6. Decision Situations: First Rule Number

Enemy Line	Enemy Encampment	Table	Rule#	Enemy Line	Enemy Encampment	<u>Table</u>	Rule_#
3	1	1	68	4]	1	96
3	1	2	71	4	1	2	99
3	1	3	41	4	1	3	45
3	1	4	12	4	1	4	11
3	1	5	3	4	1	5	12
. 3	2	1	72	4	2	1	100
3	2	2	74	4	2	2	105
3	2	3	45	4	2	3	45
3	2	4	12	4	2	4	11
3	2	5	12	 4	2	5	12
3	3	1	75	4	3	1	106
3	3	2	76	4	3	2	20
3	3	3	4	4	3	3	45
3	3	.4	12	4	· 3	4	23
3	3	5	12	4	3	5	12
3	-4	1	78	4	4	1	108
3	4	Ż	81	4	4	2	20
3	4	3	-45	4	4	3	74
3	4	4	23	4	4	4	23
3	4	5	12	4	4	5	11
3	5	1	83	4	5	1	109
3	. 5	2	61	4	5	2	32
3	5	3	88	4	5	3	20
3	5	4	23	4	5	4	34
3	5	5	12	4	5	5	23
3	6	Ĵ	89	4	6	1	111
3	6	2	94	4	6	2	113
- 3	6	3	61	4	6	3	114
, 3	6	4	34	4	6	4	34
3	6	. 5	23	4	6	5	34

Figure 6. (Continued)

Rule #	<u>≤</u> E	≤	s F	_ ≤	<u>D0</u>	ELSE
1	0	1	9	9	s ·	D
2	0	3	9	.ģ	, A	C
3	0	1	6	9	Α	С
4	0	3	6	9	Α	С
5	0	1	9	9	Α	ם
6	0	3	8	9	Α	C
7	0	2	8	9	Α	8
8	0	. 2	5	5 ,	Α	9
9	. 3	9	5	5	S	D
10	C	3	4	9	A	C
11	0	1	0	9	Α	C
12	0	1	4	9	Α	C
13	0	2	9	9	Α	14
14	0	4	8	8	Α	15
15	0	2	7	7	Α	16
16	0	4	4	5	Α	17
17	5	9	4	,5	S	18
18	0	9	0	2	S	D
19	3	4	6	7	¢	20
20	5	9	0	9	C	Α
21	0	4	9	9	Α	22
22	0	2	4	8	A	С
23	0 1	3	0	9	Α	C
24	0	5	7	9	Α	25
25	0	1	6	6	Α	26
26	0	5	4	5	Α	27
27	0	3	0	2	Α	28
28	2	. 5	6 ·	6	D	29
29	6	6	6	9	D	30
. 30	8	9	0	5	D	S

Figure 7. Expert System Game Rules

Rule #	≤	<u>≤</u>	<u>≤</u>	- ≤	DO	ELSE
61	5	6	8	8	Α	87
62	0	2	0	5	Α	63
63	3	. 4	0	7	. с	20
64	6	9	6	9	D	65
65	4	5	6	6	D	66
66	5	9	0	5	S	Α
67	5	6	6	6	С	32
68	0	1	9	9	\$	69
69	0	2	5	5	Α	70
70	0	9	0	4	S	D
71	3	3	4	8	С	52
72	0	0	7	9	Α	73
73	0	3	5	5	Α	70
74	0	2	4	9	Α	C
75	0	2	7	9	Α	73
76	3	4	6	7	С	77
77	0	. 4	0	4	С	20
78	0	3	5	9	Α	79
79	4	4	5	5	Α	80
80	0	9	4	4	S	D
81	3	4	6	6	С	82
82	0	4	0	2	С	20
83	4	4	6	6	D	84
84	0	3	0	4	Α	85
85	4	9	0	4	S	86
86	5	9	5	9	D	Α
87	. 0	4	0	9	Α	C
88	0	2	0	2	C	63
89	7	8	9	9	S	90
. 90	5	7	0	2	S	91

Figure 7. (Continued)

Rule #	≦	<u>E ≤</u>	≦	F ≤	<u>DO</u>	ELSE
31	3	6	6	6	C	32
32	7	9	0	9	C	A
33	3	4	6	6	c	20
34	0	6	0	9	Ā	C
35	0	1	9	9	S	36
36	0	1	5	5	. A	37
37	2	3	5	5	S	38
38	0	3	0	4	9	39
3 9	4	. 9	0	5	S	D
40	0	2	5	9	A	C
41	0	2	7	9	A	C
42	0	1	5	9	A	C
43	.0	0	9	9	A	44
44	ì	1	9	9	S	36
45	0	2	6	9	A	C
46	0	1	8	9	A	8
47	0	3	5	9	A	C
48	0	3	. 7	9	А	49
49	0	3	5 '	5	Α	50
50	4	5	5	5	S	D
51	3	3	6	7	С	52
52	0	3	0	2	С	53
53	4	9	0	9	С	Α
54	3 ^	3	6	8	С	55
55	0 .	3	0	5	С	53
56	0	3	7	ā	Α	· 57
57	4	5	8	8	Α	58
58	0	3	0	5	Α	59
59	4	5	0	5	S	D
60	3	4	6	6	C	61

Figure 7. (Continued)

Rule #	<u>≤ [</u>	≤	≤ [<u> </u>	DO	ELSE
91	6	7	4	5	S	92
92	8	9	0	5	D	93
9 3	6	9	6	8	D	Α
94	8	9	0	9	C	95
95	6	7	0	4	C	Α
96	. 0	4	0	2	S	97
97	0	3	4	5	A	98
98	8	9	6	7	S	A
99	0	2	0	9	Α	С
100	2	9	0	2	S	101
101	0	1	0	2	Α	102
102	0	3	4	5	Α	103
103	0	1	6	9	Α	104
104	8	9	6	8	S	D
105	3	3	6	8	С	53
106	4	9	4	. 9	D	107
107	3	9	0	2	S	A
108	5	9	4	9	D	107
109	· 6	9 .	4	9	D	110
110	4	.9	0	2	S	Α
111	5	9	0	2	S	112
112	. 6	9	4	8	D	Α
113	7	9	0	8	C	. A
114	7	9	0	9	C	115
115	5	6	Û	5	С	A

Figure 7. (Continued)

IV. EXPERIMENTAL PLAN

4.1 Objective

The objective of the experimental plan is to formulate a controlled experimental environment and procedure for assessing the expert system as a training aid and as a performance aid. The experiments are designed to verify a number of hypotheses about the usefulness of the expert system in various modes of operation. Human subjects will be enlisted to participate in the experiments and an automatic performance measurement module will be installed into the expert system to monitor the decisions made by the subjects. The following sections describe the experimental plan in more detail.

4.2 Verifiable Hypotheses

Four verifiable hypotheses have been selected for experimentation.

- H₁: Performance improves with increased level of aiding.
- H₂: As task familiarity increases, the usefulness of the expert system as a training aid increases.
- H₃: When expertise is high, the benefit of the expert system as a performance aid is lower.
- H₄: The maximum level of expert a is reached sooner when using the expert system.

Figure 8 shows the hypothesized relationship between the user's learning curve (dotted line) and the benefit of an expert system (solid line). When the user is new to the environment, aiding

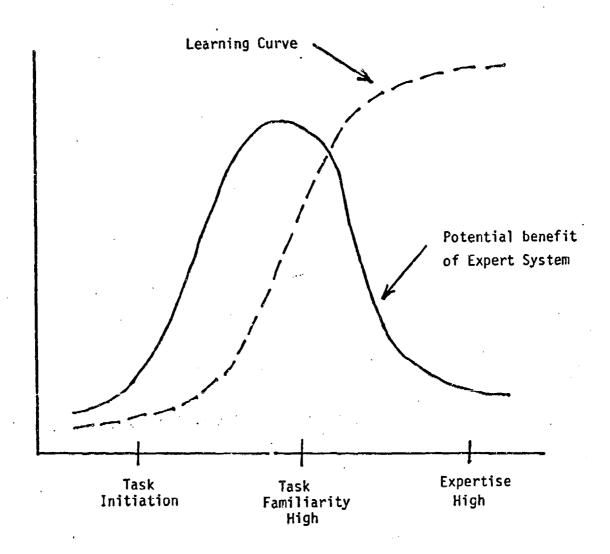


Figure 8. Potential Benefit of Expert System

of a particular subject. The subject simply plays one or more games with no aiding at all and his expertise level is the average number of correct decisions made divided by the total number decisions made.

expertise =
$$\frac{\text{correct decisions}}{\text{total decisions}}$$

A second measure of expertise is based on the actual outcomes of the decision. This measure is simply the subject's average game score over a number of successive trials.

"Task Familiarity" can be measured by combining the number of games played with the total amount of time interacting with the game environment. The "Maximum Level of Expertise" is reached when the increase in expertise from successive trials approaches zero.

max expertise reached when:

The amount of aiding chosen is simply the number of times the subject used the expert system divided by the number of times he/she could have used it (in those experiments in which there is a choice).

4.4 Performance Measures

Measures of level of performance correspond to or are functions of the measured test factors. These can be simple or aggregated measures.

- (1) Decision time as a function of expertise
- (2) Decision time as a function of task familiarity
- (3) Learning rate (increase in task familiarity over time)
- (4) Mastery rate (increase in expertise over time)
- (5) Time to reach maximum level of expertise
- (6) Increased game score over time
- (7) Expertise vs. amount of aiding used

4.5 Test Design

The test design specifies those factors that will be the objects of the test and those factors that will be eliminated in order to remove their influence on the results.

For hypothesis H₁ (See Section 4.2), the effects of factor 1 on factor 3 (See Section 4.3) will be measured. Factors 2, 4, 5, and 6 will be eliminated. Three levels of expert system aiding will be employed: full, partial, and none. With full aiding, the subjects will be able to consult the expert system any time desired. With partial aiding, only selected decisions will point siding. For experiments concerning H₁, a Latin Squaretype design will be used.

For hypotheses H_2 and H_3 , the effects of factors 1 and 6 will be assessed on factor $\Delta 3$. This means that the rate of change in level of expertise will be measured. Factors 2, 4, and 5 will be a iminated. Repeating single factor experiments will be used.

For hypothesis H_4 , the effects of factor 1 on factor 4 will be measured. Factors 2, 3, 5, and 6 will be eliminated. Again, single factor experiments with repetitions will be used.

4.6 Experimental Procedure

Every experiment will be carried out in 4 phases: (1) definition, (2) design, (3) data collection, and (4) data analysis. The definition phase will concern the precise plan for carrying out each experiment. This includes the dependent and independent variables (factors), the number of observations taken, the number of subjects, the number of experimental groups, etc. The design phase concerns the type of test performed: Latin Square, repeated single factor experiments, etc. The data collection phase will occur during the experiments and will be automated due to the implementation of the Performance Evaluation Module within the expert system. Finally, data analysis will verify or reject the proposed hypotheses.

Since continued use of the expert system during experimentation increases task familiarity and expertise, the experimentation order influences the results. Thus, a Latin Square Design is appropriate for eliminating this effect. A Latin Square is a matrix that specifies different combinations of experimental

order for the same groups of subjects. For example, in an experiment with three levels of aiding (full, partial, and none), three groups of subjects would participate in different orders with the levels. (See Figure 9). Thus, group A would use full aiding first, partial aiding second, and no aiding third. However, group C would use no aiding first, full aiding second, and partial aiding third, etc. In addition to the Latin Square, other economical designs will be used according to Crolotte, A. and Dechter, R., "Plan for TCO Testing and Evaluation", Perceptronics Report PFTR-1082-11-79, November 15, 1979. These designs include one-factor two-level experiments such as randomized repetition, cross-over repetition, and non-rectangular Latin Squares, etc. (See Figure 10)

Data analysis for these designs consists of a one-way analysis of variance (ANOVA). A summary of the one-way ANOVA method is described in Figure 11.

	•	•		
EXPERIMENT ORDER	•	NO AIDING	PARTIAL AIDING	FULL AIDING
1	+	C ·	В	A
2		В	A	С
3		. A	C	В

Figure 9. Latin Square Design

ME FACTOR - 2 LEVEL EXPERIPERT

	*				
Number of Subjects per Experiment	Preferred and Alternative Designs	Total Number of Subjects Required	Number of fests per Subject	Number of df per Error	Coments
1	10 crass-over	92	~	•	Very powerful design affording a high number of degrees of freedom for the error but fairly costly in number of subjects.
	7 cross-over	8	2	\$	Powerful design requiring less subjects and still paretding the minimum number of degrees of freedup for the error.
	6 randomized blocks	•	~	w	Design requiring less subjects than cross-over for the same number of degrees of freedom for the error. It is, however, implicitly assumed that no position effect exists.
~	7 cross-over	=	~	s	Same as above.
• •	6 randomized blocks	~	~	\$	Same as above.
e.	'4 cross-over with repetition	21	4	+	If no treatment a cross-over effect exists, the number of degrees of freedom for the error is 5.
	4 randomized blocks with repetition	12	•	•	If no treatment a block effect eaists, the number of degrees of freedom for the error is 7. No Position effect essured.
*	4 cross-over with repairition	91	•	•	Same as above.
•	3 randomized blocks with repetition	21	7	4	If no treatment a block effect axists, the numer of degrees of freedom for the error is 5. No position effect assumed.
10	3 randomized blocks with repetition	2 IS	•	-	Same as above.

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Figure 10. Contingency plans for one-factor 2-level experiments.

ONE-WAY ANALYSIS OF VARIANCE

One Way ANOWA

Source	Degrees of freedom (df)	Sum of Squares (SS)	Mean of Squares (MS)
Between Alternatives	k-1	$SS_{alt} = \sum_{j=1}^{k} \frac{T_{.j}^2}{n_j} - \frac{T^2}{N}$	$MS_{alt} = \frac{SS_{alt}}{k-1}$
Within Alternatives or Error	N-k	$\sum_{j=1}^{k} \sum_{i=1}^{n_{j}} y_{ij}^{2} - \sum_{j=1}^{k} \frac{T_{ij}^{2}}{n_{j}}$	MS _{err} = SS _{err}
Totals	N-1	$\sum_{j=1}^{k} \sum_{i=1}^{n_j} y_{ij}^2 - \frac{\tau^2}{N}$	

Where $y_{i,j} = observation i of alternative j.$

k = number of alternatives.

 n_j = number of observations for alternative j.

$$N = \sum_{j} n_{j}$$

$$T_{-j} = \sum_{i=1}^{n_j} y_{ij} = \text{total for alternative j.}$$

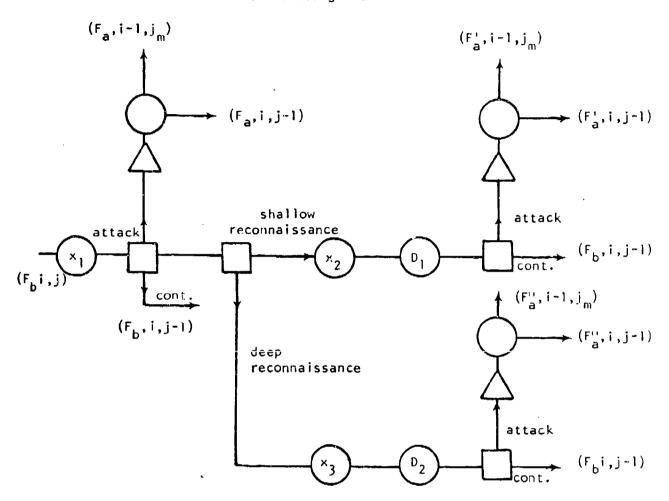
T = Grand total.

Figure 11. One-way analysis of variance.

APPENDIX A

DECISION DIAGRAM FOR GAME

The following decision diagram shows the decision points, event points, report points, and identification points for the Scenario Generator game.



Flow-diagram for data and decisions in the (i,j) stage. The triplet (F,i,j) denotes the state of entering the (i,j) stage with force F.

Random Variables

 $F_b \sim 0$ wn force on entry

F - Own force after an attack

 x_1 - Initial report regarding enemy strength

 x_2 - Report obtained by shallow reconnaissance

 x_{γ} - Report obtained by deep reconnaissance

D₁ - Being detected during shallow reconnaisance

 \mathbf{D}_{2} - Being detected during deep reconnaissance

APPENDIX B

DECISION TABLES FOR THE GAME

The following tables show the optimal decisions for all encountered situations in the Scenario Generator game.

1 (I=4, J=7)		######################################
ENCAMPMENT		5
ENERY L No. 1 ENC	MATALLAMANICLAMA	# 000000000000000000000000000000000000
W	10 X 10	19
DECISION MAP	ATTACK/CONTINUE HHH HHH HHH HHH NAM NAM NAM HHM HHM HHM HHM HHM NAM NAM NAM NAM NAM NAM NAM NAM NAM NA	ATTACK/CONTINUE HITH HITH HITH HITH HITH HITH HITH HIT

DECISION	FIAP		ENEMY LINE 1	ENCAMPMENT 2	(I=4, J=6)	
A4 14 A6 A6 A6 A6 A6 A6 A6 A6 A6 A6 A6 A6 A6 A	HATTEREFE N N	SHA	THING TO THE TOTAL CANADA TO THE TOTAL CANADA TO THE TOTAL CANADA CANADA TOTAL CANADA	LLMWMMNLLHHNN/MHHNMMNLLHNN/MHNMMNLHNN/MHNMMNLHNLHNHNMMNLHNLHNHNMMNLHNLHNLMHNMMNLHNLHNLHNHNMMNLHNLHNLHNLHNHNMMNLLHNN/MHNMMNLLHNN/MHNMMNLLHNN/MHNMMNLHNNMMNLLHNN/MHNMMNLHNN/MHNMMNLHNN/MHNMMNLHNN/MHNMMNLHNN/MHNMMNLLHNN/MHNMMNLLHNN/MHNMMNLLHNN/MHNMMNLLHNN/MHNMMNLLHNN/MHNMMNLLHNN/MHNMMNLLHNN/MHNMMNLLHNN/MHNMMNLLHNN/MHNMMNLLHNN/MHNMMNLLHNN/MHNMMNLHN/MHNMMNLHNN/MHNMMNLHNN/MHNMMNLHNN/MHNMMNLHNN/MHNMMNLHNN/MHNMMNLHNN/MHNMMNLHNN/MHNMMNLHNN/MHNMMNLHNN/MHNMMNLHNN/MHNMMNLHNN/MHNMMNLHNN/MHNMMNLHNN/MHNMMNLHNN/MHNMMNLHNN/MHNMMNLHNN/MHNMMNLHNN/MHNMMNLHNN/MHNMMNLHNM	ICONTO CONTO	
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DECISION MAP		ENEMY	LINE 1	ENCAMPMENT	m	(] = 4,	J=5)	
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ATTACK/CONTINOE CLATAC HANN HANN HANN HANN CLATAC NAME NAME NAME NAME NAME NAME NAME NAME			00000000000000000000000000000000000000	#	00000000000000000000000000000000000000	60000000000000000000000000000000000000	90000000000000000000000000000000000000	
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ENEMY LINE I ENCAMPMENT 4 (I=4, J=4) NNNLALLNNMLLMANLALLMANNALLHMANMAHALLHLMANHAHLHMANHHHH NNLALLNNMLLMANLALLMANNALLHMANMAHALLHLMANHHHHHHHHHH	0000000000
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(1=4, J=3)	NILTALLNAMLLANALLAMNAMILLHANNAMILLHLMANHHLLMAHHMLHMHHHHHHHHHHHHHHHHHHHHH	C
ENCAMPMENT 5	MMUNHLLMUNMMNLLHHNWMMHTHT NLWHWLMLMMMNLLHMWMMN CREPGE XIN XI ODDAADDDDDDDDDDDDDDDDDDDDDDDDDDDDDDDDD	
ENEMY LINE 1	NAL-INCLINAL INC. NAL-INCLINAL INC. NAL-INCLINAL INC. NAL-INCLINAL INC. AAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAA	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
DECISION MAP	ATTACK/CONTINUE/S HHH HHH HHH HHH NYA NYA NYA NYA HHH HHH HHH HHH HHH HHH NYA	ATTACK/CONTINGE HEHE HEHE HEHE HEHE HEHE HEHE HEHE H

ENCAMPMENT 6 (I=4, J=2)	HLLMNIMMNILLHHINMMHHLLHLMMNHHLLMMHHMLHHMMHHHH NILLIANHLHNLNHMHHHLLMILHMHMHLLMMHI NILLIANHLHNLNHMNHHLLMILHMHMHLLMMHHHHHM ORT X 1) AAAAAAAAAAAAAAAADDDDDAAADDDDDDDDDDDDD	DDDDDDDSDSSSDSDSSSSSSSSSSSSSSSSSSSSSSS	CACCCCC CACCCCC CACCCCCCCCCCCCCCC	AAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAA	NIM CCAA NIM CCAA
DECISION MAP ENEMY LINE 1	HAIRICHTANNICHTE	5	AANAAAACACACACACACACACACACACACACACACACA	P. S. C.	

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DECISION MAP		ENEMY	Y LINE	ᆔ		Ū	ENCAMPMENT	MENT	~		(1=4,		√=1			
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DECISION MAP	ATTACK/CONTINGE/SHA MANAGE AND

DECISION MAP	ENEMY LINE 2 ENCAMPMENT 2 (1=3, J=6)	
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DECISION MAP	ENEMY LINE 2 ENCAMPMENT 3 .(1=3, J=5)
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DECISION MAP	ENEMY	LINE 2	ENCAMPMENT 4	(1=3.	J=4)
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DECISION MAP		ENEMY	LINE 2	ENCAMPMENT 5	(E=I)	J=3)
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DECISION MAP		ENEMY LINE 2 ENCAMPMENT & (I=3, J=2)	
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OPTIMALITY March 6, 1982

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DECISION MAP		ENEMY L	LINE 3	ENCAMPMENT 2	(I=2,	. (9=€
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DECISION	MAP	FINE	Y LINE 3	ENCAMPMENT 4	(I=2,	J=4)
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DECISION M	MAG	ENEMY LINE 4 ENCAMPMENT 1 (I=1, J=7)	
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DECISION	MAP.		ENEMY L	LINE 4	ENCAMPMENT 3	([=])	J=5
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DECISION MAP		ENEMY LINE 4 (I=1, J=4)
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ENERY LINE 4 ENCAMPMENT 5 (I=1, J=3) NNNLNLENNTLIMMENTELIMMENTEL HYNNMMHHELHEMMHHELHEMMHHEHMMHHHHMMHHHMMHHELMMHHELMMHHELMMHHHMMHHHMMHHHMMHHHMMHHHMMHHHMMHHHMMHHHMMHHHMMHHHMMHHHMMHHHMMHHHMMHHMHHMHHHMMHHHMMHHHMMHHHMMHHHMMHHHMMHHHMMHHMHHMHHMHHMHHMHHMHHMMHHMHHMHHMMHMH	CCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCC	AAAAAA	(REPORT X3) H-H TH-H TH-H
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BECISION MAP ENERY LINE 4 ENCAMPAGNATUR LINE LINE HIGH LINE HIGH LINE HIGH HIGH HIGH HIGH HIGH HIGH HIGH HIG
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OPTIMALITY March 6, 1982

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ENEMY LINE 4	NNVLNLLNNTLNLLNNTLNNLLNNNLLNNNLLNNNLLNN
MAP E	N
DECISION M	ATTACK/CONTINUE/SHA HHH HHH NAMA NAMA NAMA NAMA NAMA NAMA